



Ultrasound Imaging based on the Variance of a Diffusion Restoration Model

EUSIPCO - Advances in Computational Ultrasound Imaging

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Presenter: Yuxin Zhang

27 - Aug - 2024



ROAD MAP

1. Introduction

Ultrasound Imaging, Despeckling, and SOTA

2. Method

Diffusion Models and the Application on Ultrasound

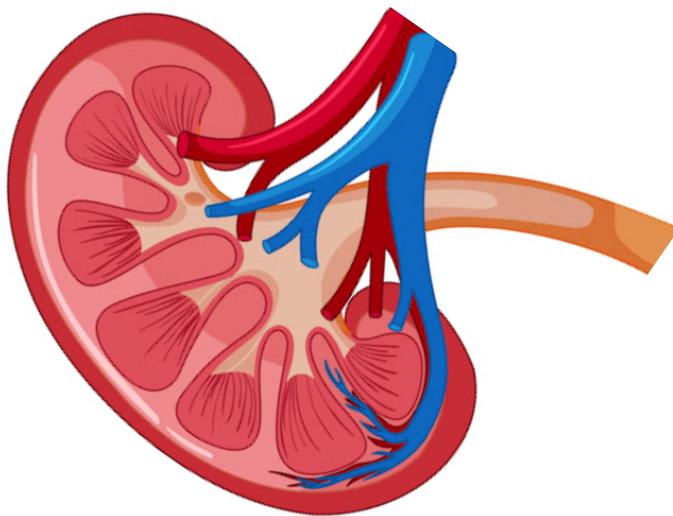
3. Results

Quantitative & Qualitative Comparison

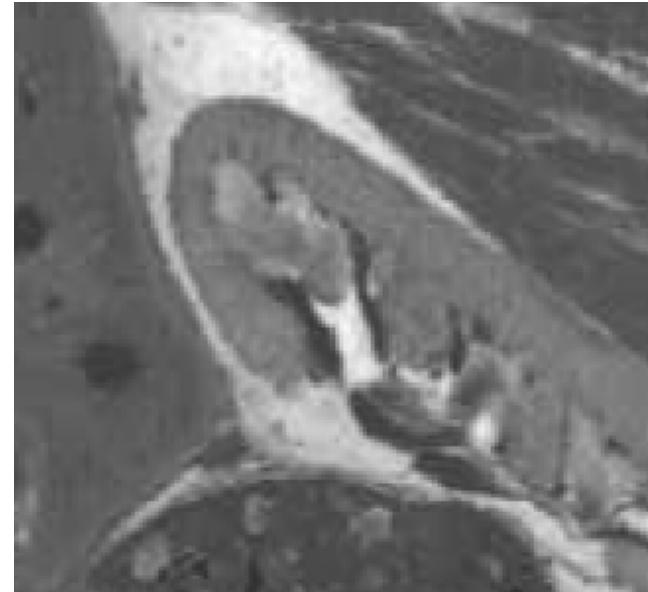
4. Conclusion

Take-home Message

Why Ultrasound Despeckling

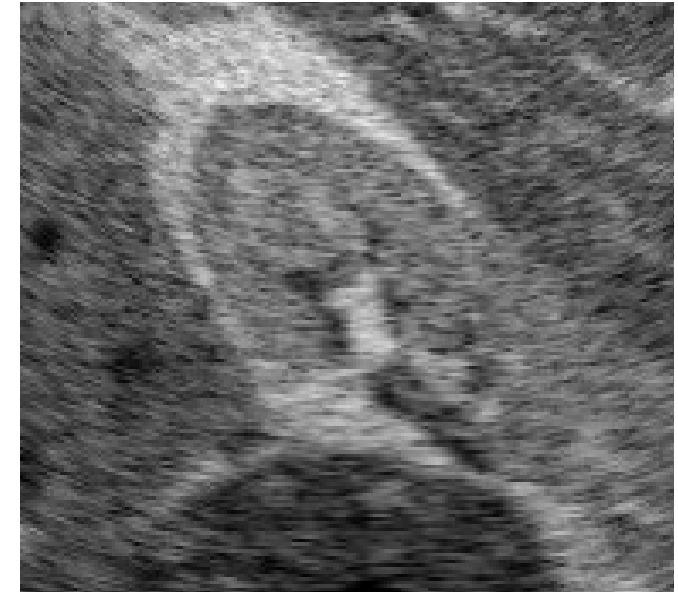


Echogenicity map



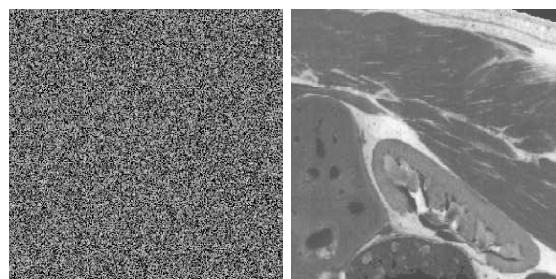
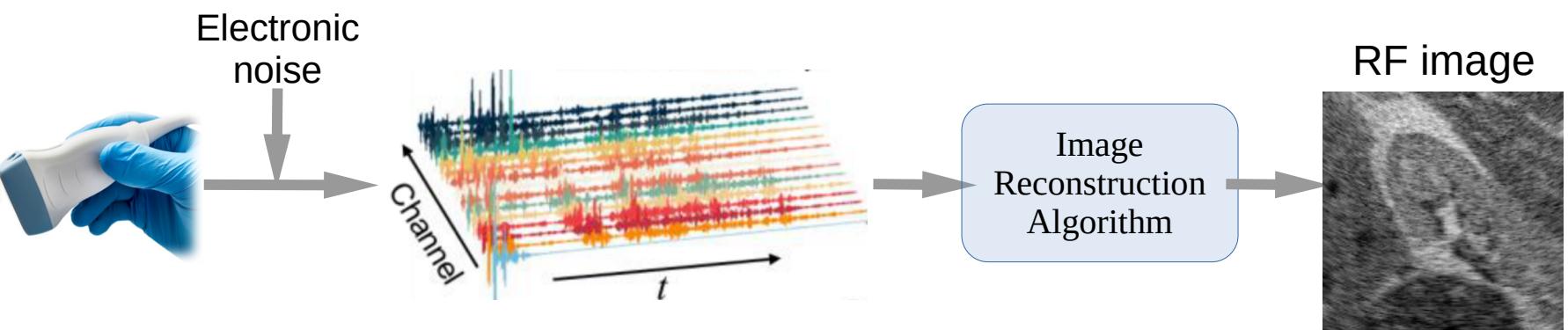
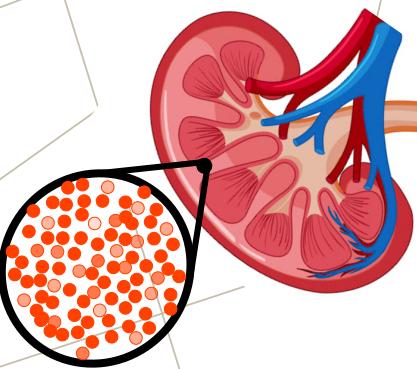
(average property of the tissue)

Observation



Ultrasound Despeckling enhances organ and tumor Classification and Segmentation.

Approximation of the Ultrasound Imaging Process



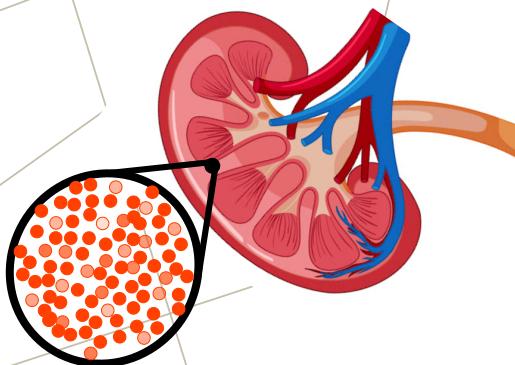
Random field
 $\sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

$$\mathbf{m} \odot \mathbf{p}$$

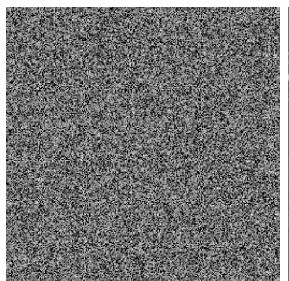
$$\begin{array}{ccccc}
 & \mathbf{H}^{\text{forward operator}} & \xrightarrow{\quad\quad\quad} & \mathbf{y} & \xrightarrow{\quad\quad\quad} \mathbf{B}^{\text{backward operator}} \\
 \mathbf{m} \odot \mathbf{p} & \longrightarrow & & \mathbf{y} & \longrightarrow \mathbf{By} \\
 & & & \mathbf{\tilde{n}} \oplus & \\
 & & & & \text{DAS-type Reconstruction}
 \end{array}$$

$$\mathbf{By} = \mathbf{BH}(\mathbf{m} \odot \mathbf{p}) + \mathbf{B}\mathbf{\tilde{n}}$$

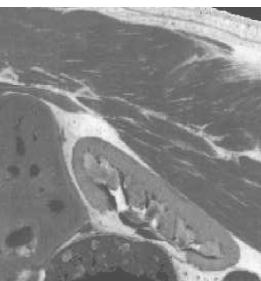
Approximation of the Ultrasound Imaging Process



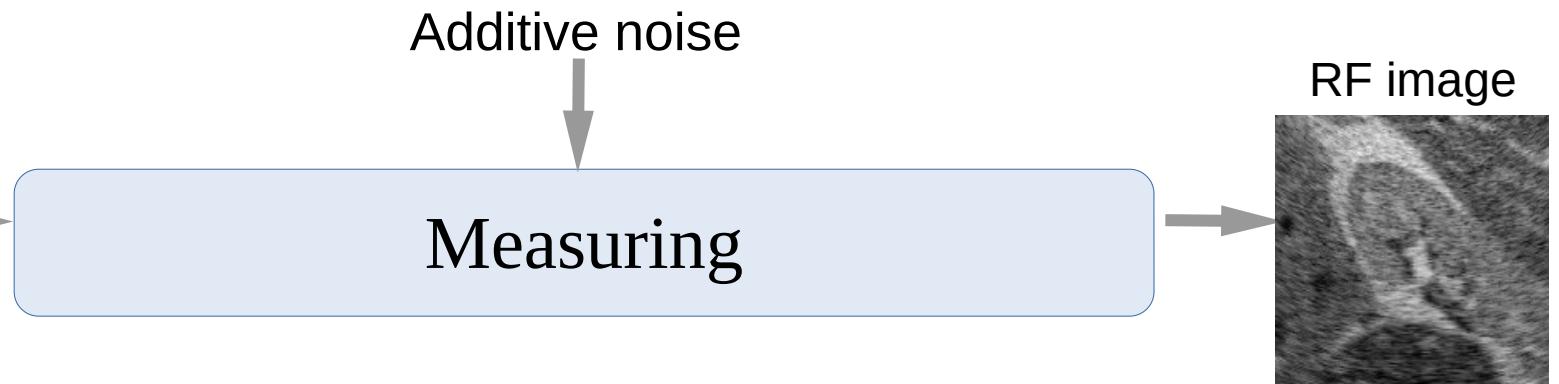
$$\mathbf{m} \odot \mathbf{p}$$



Random field
 $\sim \mathcal{N}(\mathbf{0}, \mathbf{I})$



Echogenicity map



$$\mathbf{f} = \mathbf{A}^{\text{PSF}} \mathbf{m} \odot \mathbf{p} + \mathbf{n}$$

$$\mathbf{f} = \mathbf{A} (\mathbf{m} \odot \mathbf{p}) + \mathbf{n}$$

$$\mathbf{By} = \mathbf{BH}(\mathbf{m} \odot \mathbf{p}) + \mathbf{B}\tilde{\mathbf{n}}$$

State-of-the-Art of Ultrasound Despeckling

Model 1

$$\underbrace{\mathbf{f}}_{\text{RF image}} = \underbrace{\mathbf{A} \left(\underbrace{\mathbf{m}}_{\text{PSF}} \odot \underbrace{\mathbf{p}}_{\sim \mathcal{N}(\mathbf{0}, \mathbf{I})} \right)}_{\text{PSF}} + \underbrace{\mathbf{n}}_{\sim \mathcal{N}(\mathbf{0}, \sigma \mathbf{I})}$$

[James Ng, IEEE TUFFC, 2007] (Wavelet)

State-of-the-Art of Ultrasound Despeckling

Model 1

$$\underbrace{\mathbf{f}}_{\text{RF image}} = \underbrace{\mathbf{A} \left(\underbrace{\mathbf{m}}_{\text{PSF}} \odot \underbrace{\mathbf{p}} \right)}_{\sim \mathcal{N}(\mathbf{0}, \mathbf{I})} + \underbrace{\mathbf{n}}_{\sim \mathcal{N}(\mathbf{0}, \sigma \mathbf{I})}$$

[James Ng, IEEE TUFFC, 2007] (Wavelet)

Model 2

$$\underbrace{\mathbf{f}'}_{\text{Env|RF image}} = \underbrace{\mathbf{m}'}_{\sim \text{Rayleigh Distr.}} \odot \underbrace{\mathbf{p}} + \underbrace{\mathbf{n}'}_{\text{neglected}}$$

[S. Aja-Fernandez, IEEE TIP, 2006, K. Krissian, TIP, 2007, G. Ramos-Llordén, TIP 2015, J. Xu, Signal Process. 2016] Anisotropic Diffusion
 [S. Balocco, Ultrasound Med. Biol., 2010] Bilateral Filter
 [Y. Yue IEEE TMI 2006] Wavelet
 [D. Mishra, ICPR, 2018, C.-C. Shen, Sensors, 2020] ML

Model 3

$$\underbrace{\log(\mathbf{f}')}_{\log(\text{Env|RF image})} = \log(\mathbf{p}) + \log(\mathbf{m}')$$

[S. Gupta, IEEE Vision, Image and Signal Processing, 2005, M. I. H. Bhuiyan, Int. Symp. Circuits and Systems, 2007, S. Esakkirajan, Ultrasound Med. Biol, 2013] Wavelet

Model 4

$$\underbrace{\log(\mathbf{f}')}_{\log(\text{Env|RF image})} = \log(\mathbf{p}) + \log(\mathbf{p})^{0.5} \underbrace{\log(\mathbf{m}')}_{\sim \mathcal{N}(\mathbf{0}, \sigma' \mathbf{I})}$$

[F. Argenti, J. Adv. Signal Process. 2003, Y. Yue TMI 2006] Wavelet
 [P. Coupe, IEEE TIP, 2009] NonLocal Means
 [K. Krissian, CVPR, 2005] Anisotropic Diffusion

State-of-the-Art of Ultrasound Despeckling

Model 1

$$\underbrace{\mathbf{f}}_{\text{RF image}} = \underbrace{\mathbf{A} \left(\underbrace{\mathbf{m}}_{\text{PSF}} \odot \underbrace{\mathbf{p}}_{\sim \mathcal{N}(\mathbf{0}, \mathbf{I})} \right)} + \underbrace{\mathbf{n}}_{\sim \mathcal{N}(\mathbf{0}, \sigma \mathbf{I})}$$

[James Ng, IEEE TUFFC, 2007] (Wavelet)

Model 2

$$\underbrace{\mathbf{f}'}_{\text{Env|RF image}} = \underbrace{\mathbf{m}'}_{\sim \text{Rayleigh Distr.}} \odot \underbrace{\mathbf{p}} + \underbrace{\mathbf{n}'}_{\text{neglected}}$$

[S. Aja-Fernandez, IEEE TIP, 2006, K. Krissian, TIP, 2007, G. Ramos-Llordén, TIP 2015, J. Xu, Signal Process. 2016] Anisotropic Diffusion
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 [E. Nishida, TMI, 2018, C.-C. Shen, Sensors, 2020] ML

Model 3

$$\underbrace{\log(\mathbf{f}')}_{\log(\text{Env|RF image})} = \underbrace{\log(\mathbf{p})}_{\log(\text{Env|RF image})} + \underbrace{\log(\mathbf{m}')}_{\sim \text{Rayleigh Distr.}}$$

We adapt the most realistic model,

estimating \mathbf{p} by solving an Inverse Problem.

[S. Gupta, IEEE Vision, Image and Signal Processing, 2005, M. I. H. Bhuiyan, Int. Symp. Circuits and Systems, 2007, S. Esakkirajan, Ultrasound Med. Biol., 2013] Wavelet

Model 4

$$\underbrace{\log(\mathbf{f}')}_{\log(\text{Env|RF image})} = \underbrace{\log(\mathbf{p})}_{\log(\text{Env|RF image})} + \underbrace{\log(\mathbf{p})^{0.5} \underbrace{\log(\mathbf{m}')}_{\sim \mathcal{N}(\mathbf{0}, \sigma' \mathbf{I})}}_{\sim \mathcal{N}(\mathbf{0}, \sigma' \mathbf{I})}$$

[F. Argenti, J. Adv. Signal Process. 2003, Y. Yue TMI 2006] Wavelet
 [P. Coupe, IEEE TIP, 2009] NonLocal Means
 [K. Krissian, CVPR, 2005] Anisotropic Diffusion

Overview of the Proposed Method

Model 1

$$\underbrace{\mathbf{f}}_{\text{RF image}} = \underbrace{\mathbf{A}}_{\text{SIR(PSF)}} \left(\underbrace{\mathbf{m} \odot \mathbf{p}}_{\sim \mathcal{N}(\mathbf{0}, \mathbf{I})} \right) + \underbrace{\mathbf{n}}_{\sim \mathcal{N}(\mathbf{0}, \sigma \mathbf{I})}$$



!!! Not the Anisotropic Diffusion
But a Generative Model !!!

STEP

1

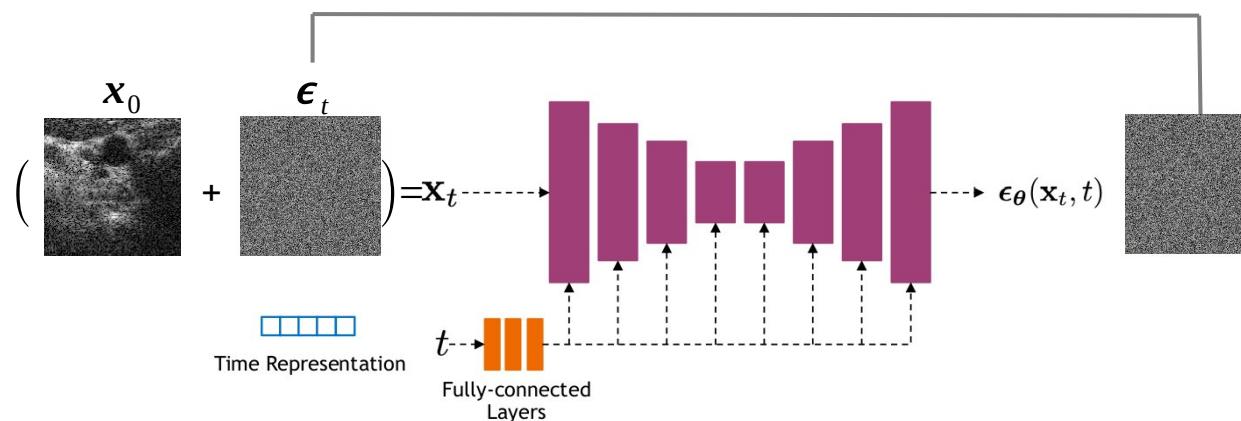
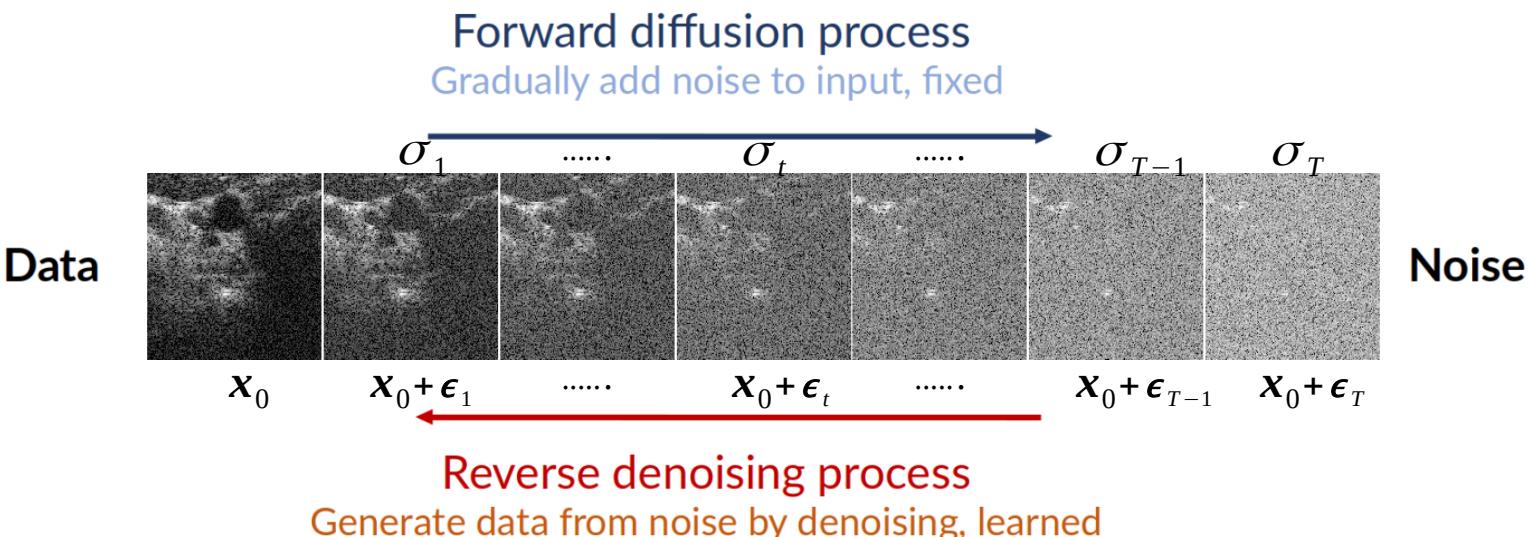
Estimate $\mathbf{m} \odot \mathbf{p}$ via a Diffusion Inverse Problem Solver

STEP

2

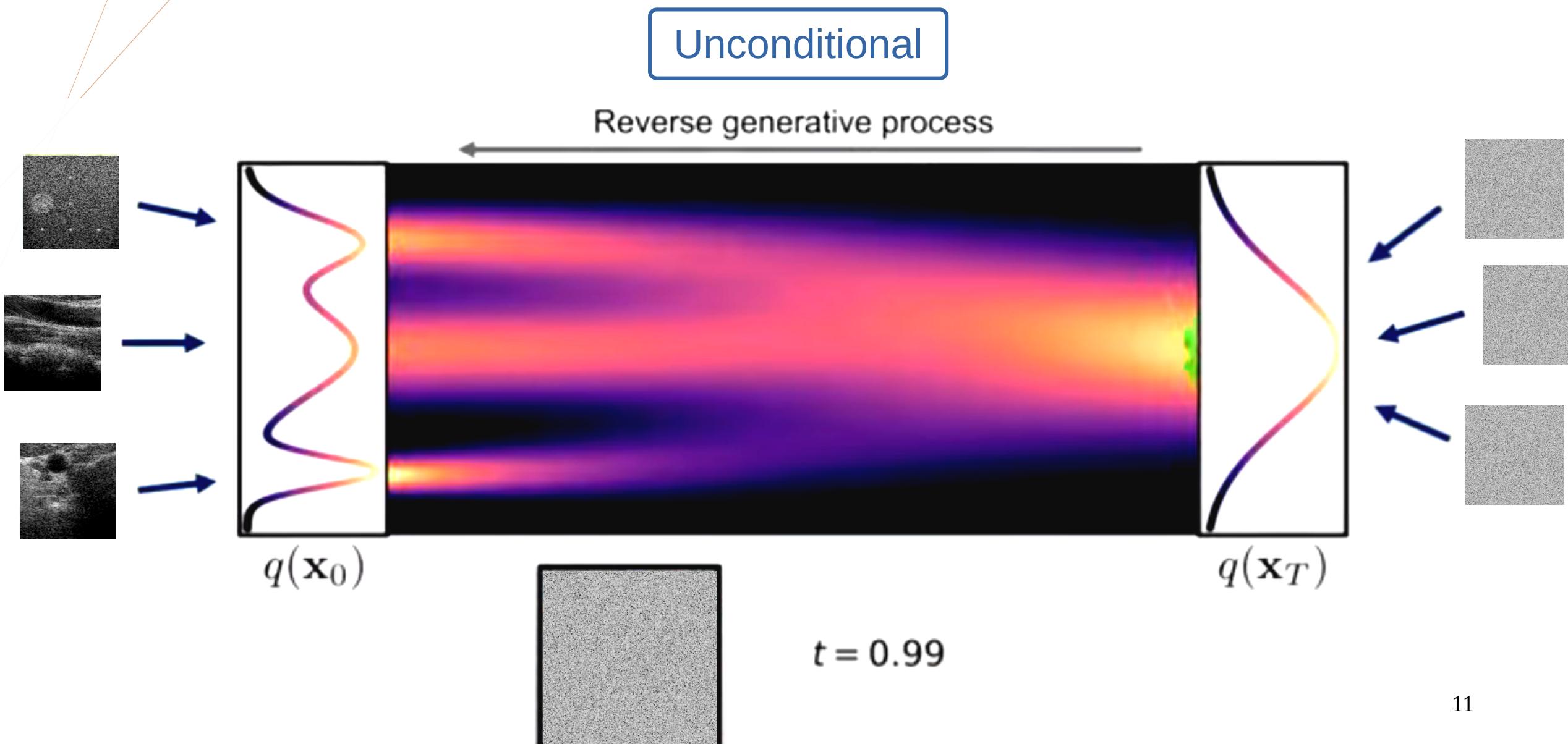
Estimate \mathbf{p} by leveraging the stochasticity of the generative sampling

Denoising Diffusion Generative Models

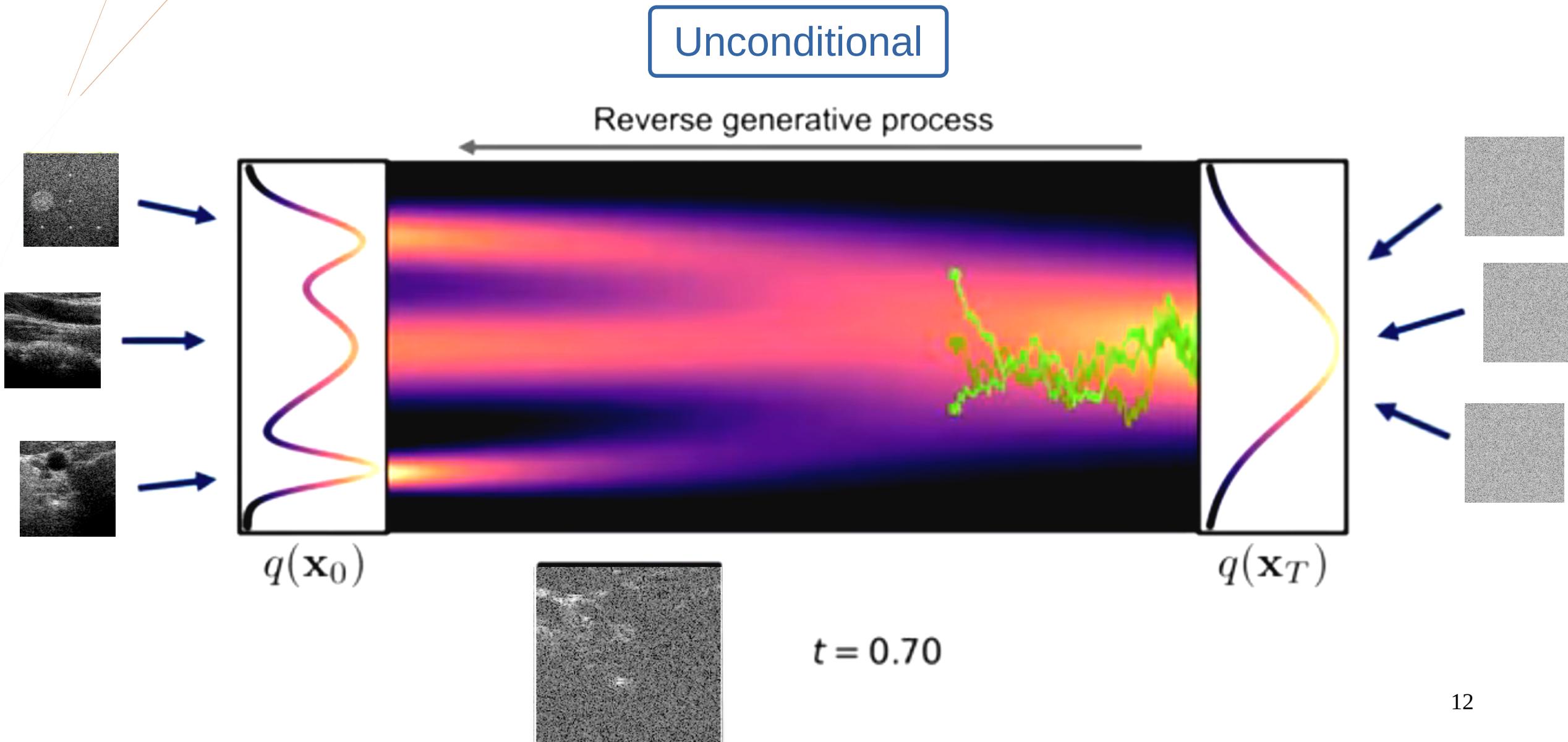


$$\text{simpleLoss} = \mathbb{E}_{x_0 \sim p_{\text{data}}} \mathbb{E}_{\epsilon_t \sim \mathcal{N}(\mathbf{0}, \sigma_t I)} \| \epsilon_\theta(x_t, t) - \epsilon_t \|_2^2$$

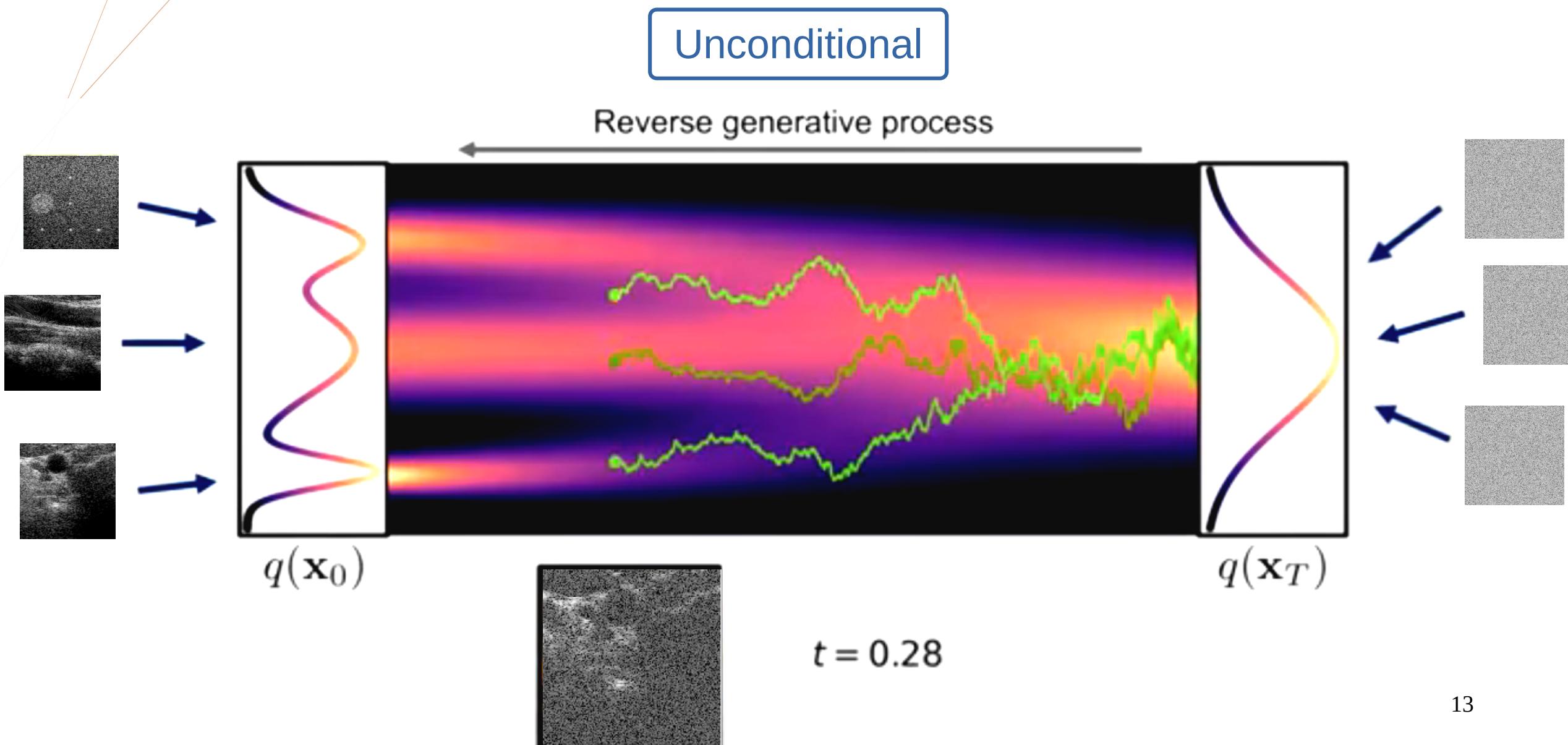
Diffusion Generative Process



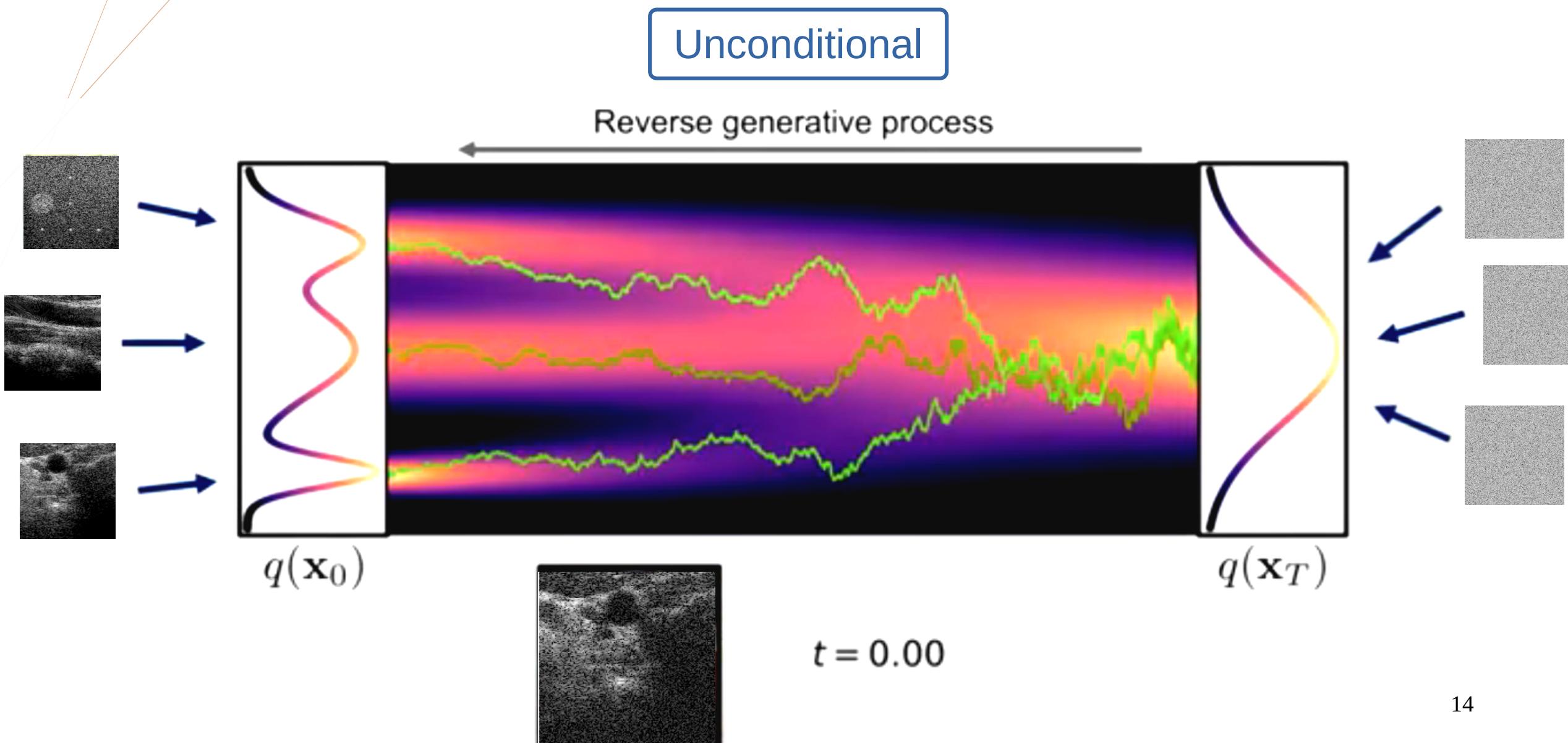
Diffusion Generative Process



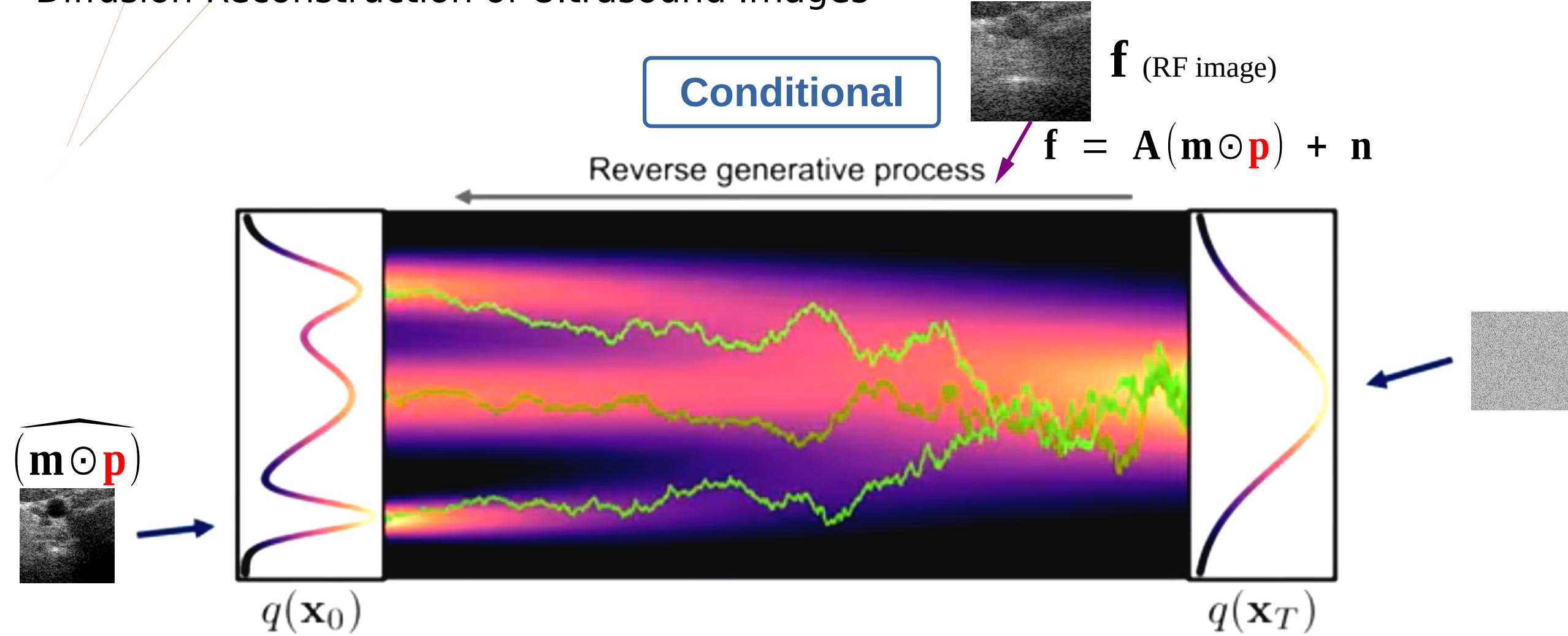
Diffusion Generative Process



Diffusion Generative Process



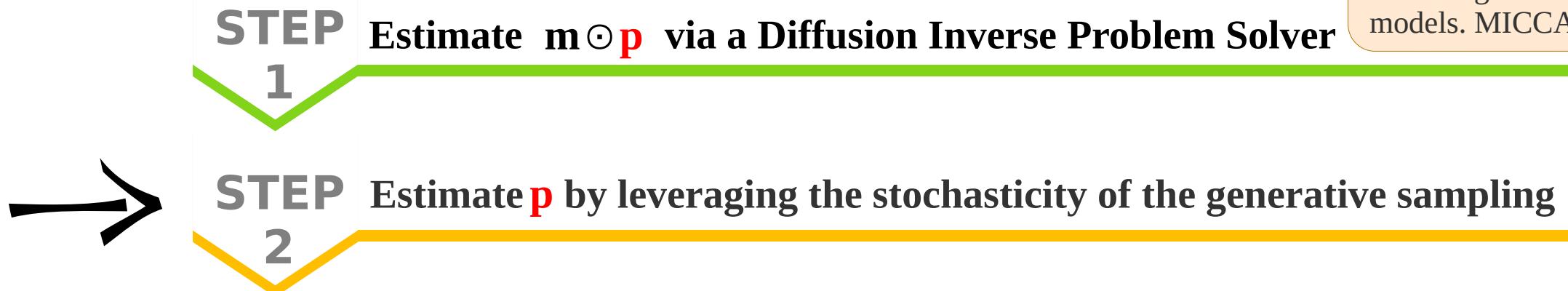
Diffusion Reconstruction of Ultrasound Images



Overview of the Proposed Method

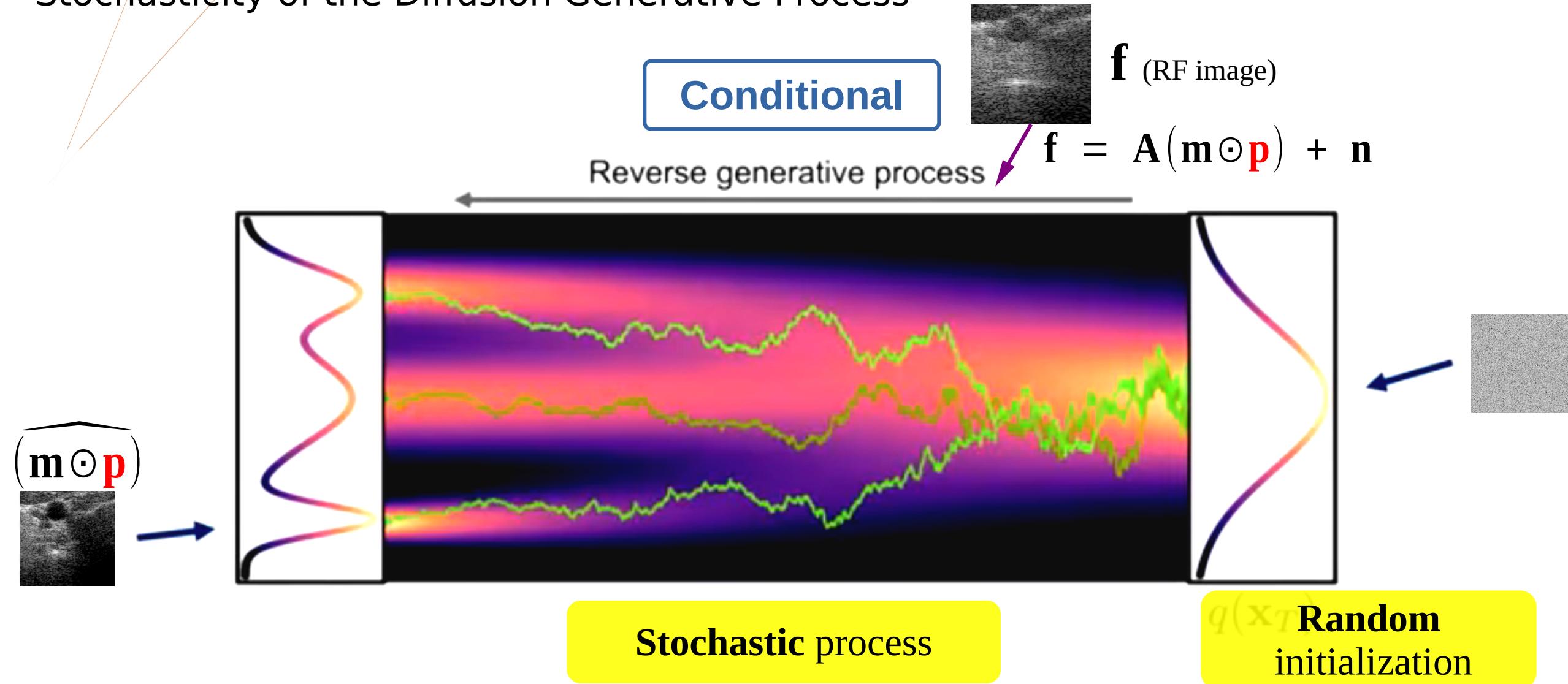
Model 1

$$\underbrace{\mathbf{f}}_{\text{RF image}} = \underbrace{\mathbf{A}}_{\text{SIR(PSF)}} \left(\underbrace{\mathbf{m} \odot \mathbf{p}}_{\sim \mathcal{N}(\mathbf{0}, \mathbf{I})} \right) + \underbrace{\mathbf{n}}_{\sim \mathcal{N}(\mathbf{0}, \sigma \mathbf{I})}$$

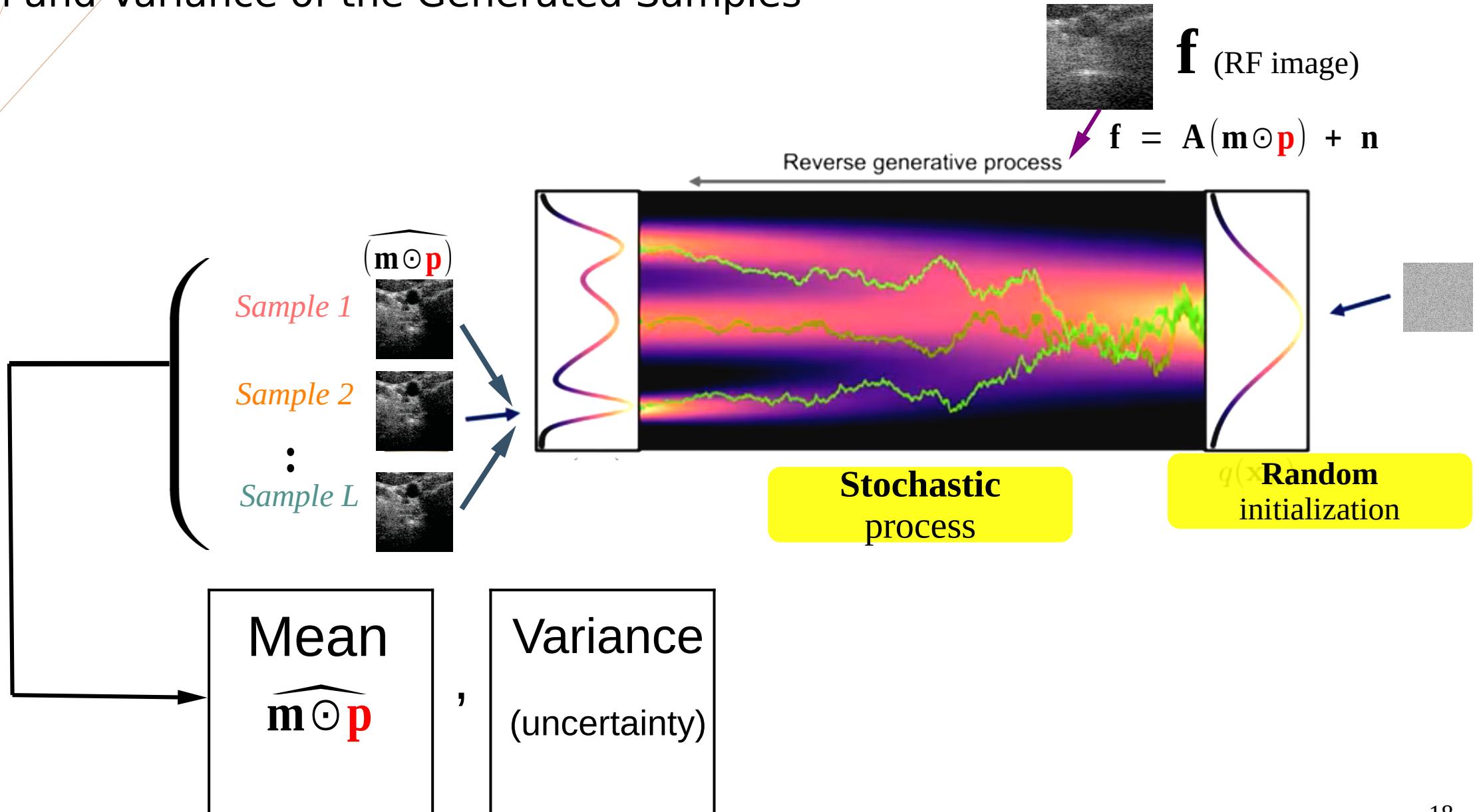
Y. Zhang et al., Ultrasound image reconstruction with denoising diffusion restoration models. MICCAI, 2023

Stochasticity of the Diffusion Generative Process

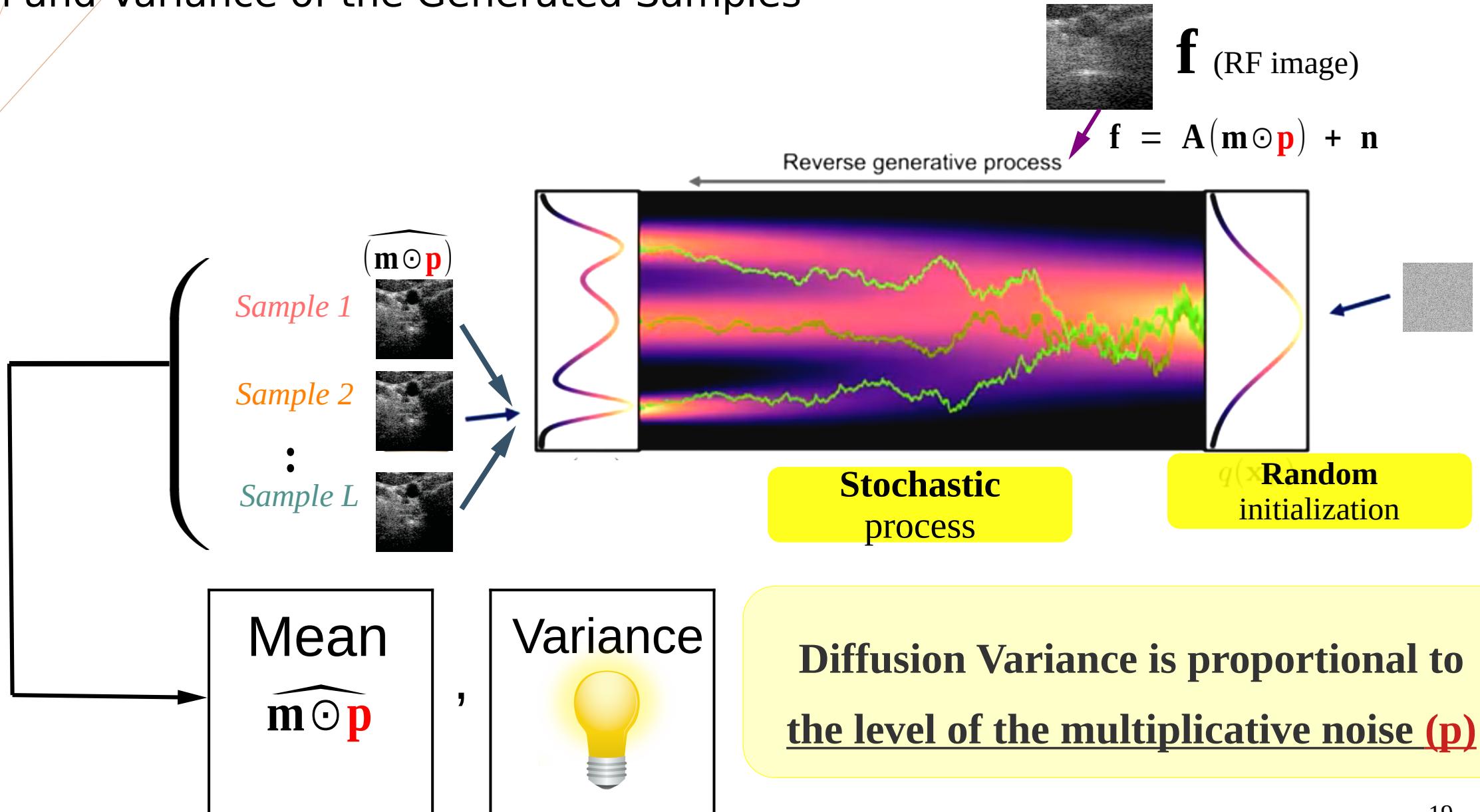


We can generate unlimited number of **different reconstructions** from a **single observation**

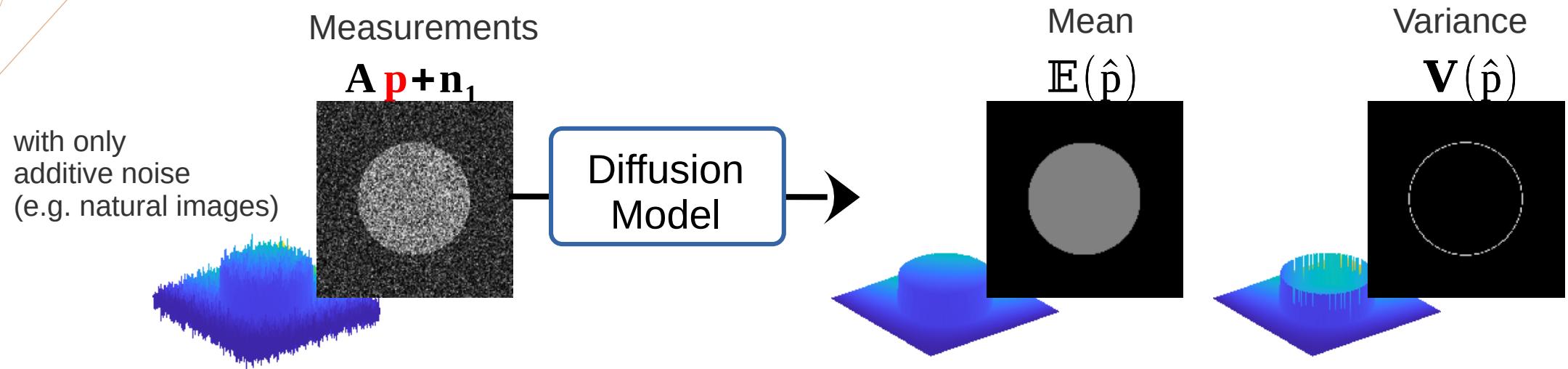
Mean and Variance of the Generated Samples



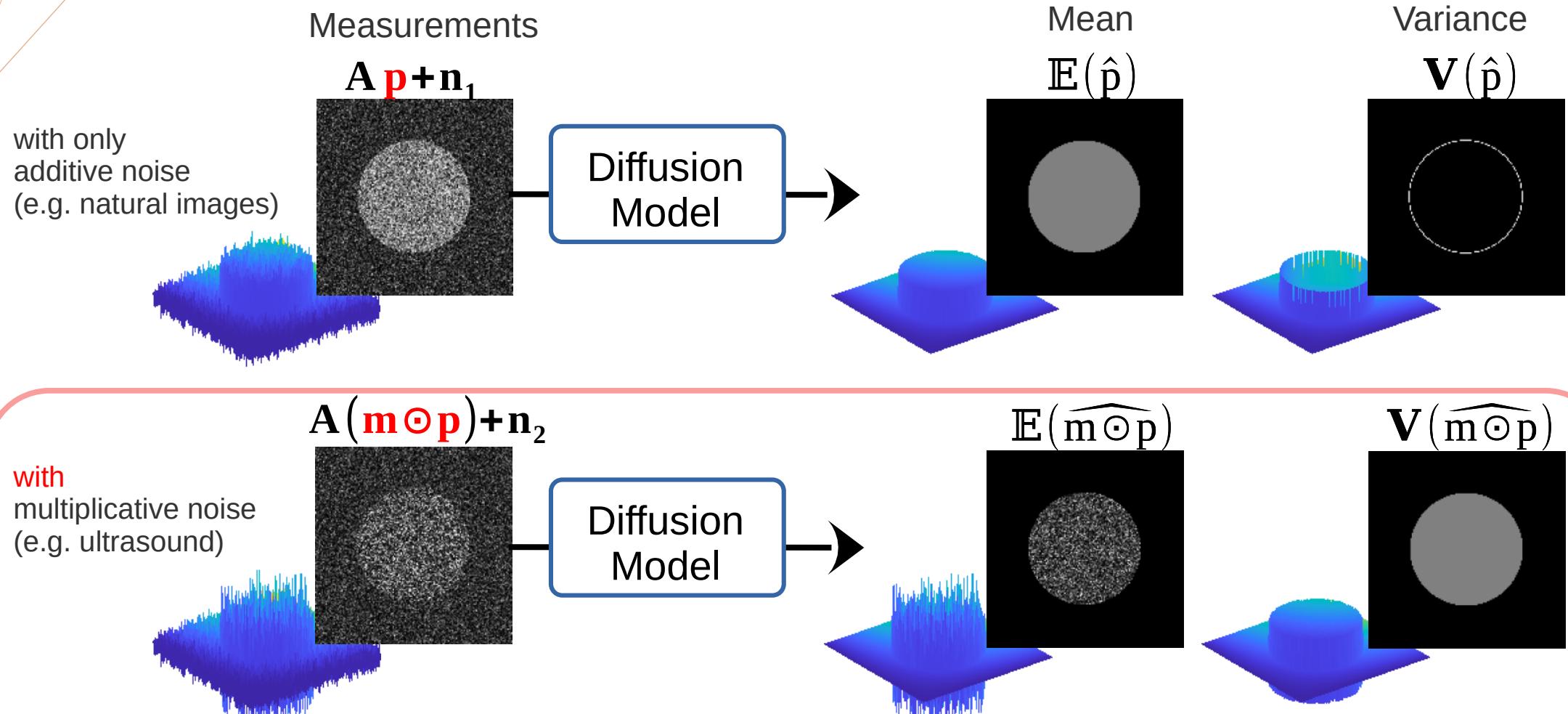
Mean and Variance of the Generated Samples



Diffusion Variance Behavior



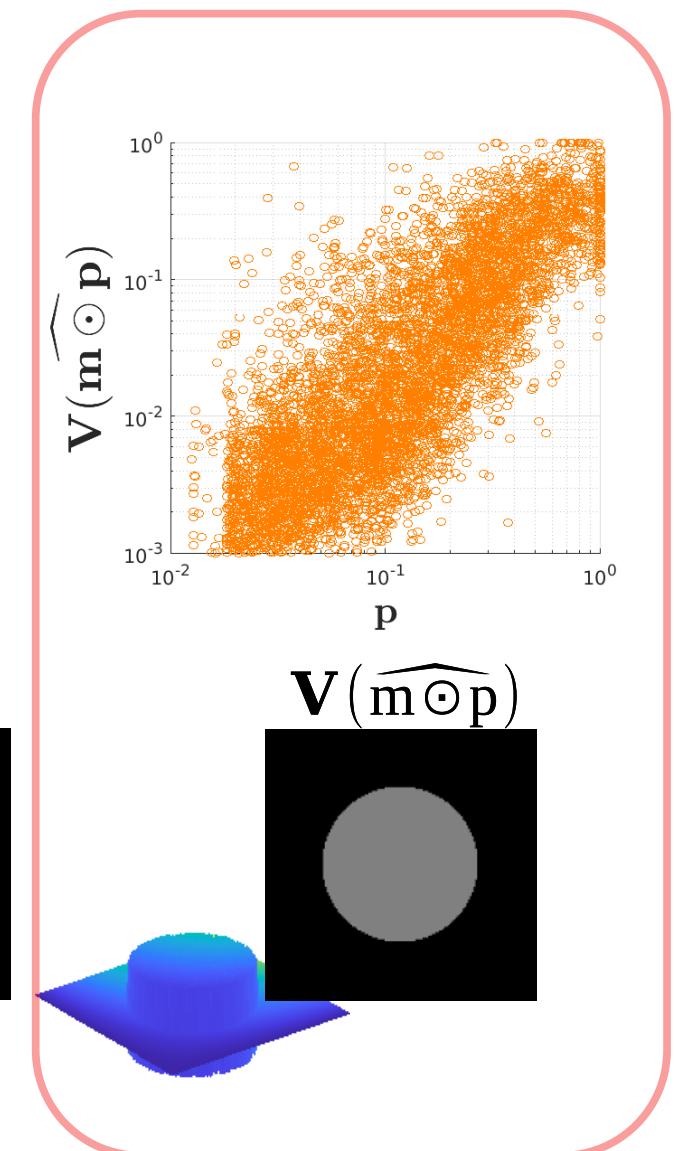
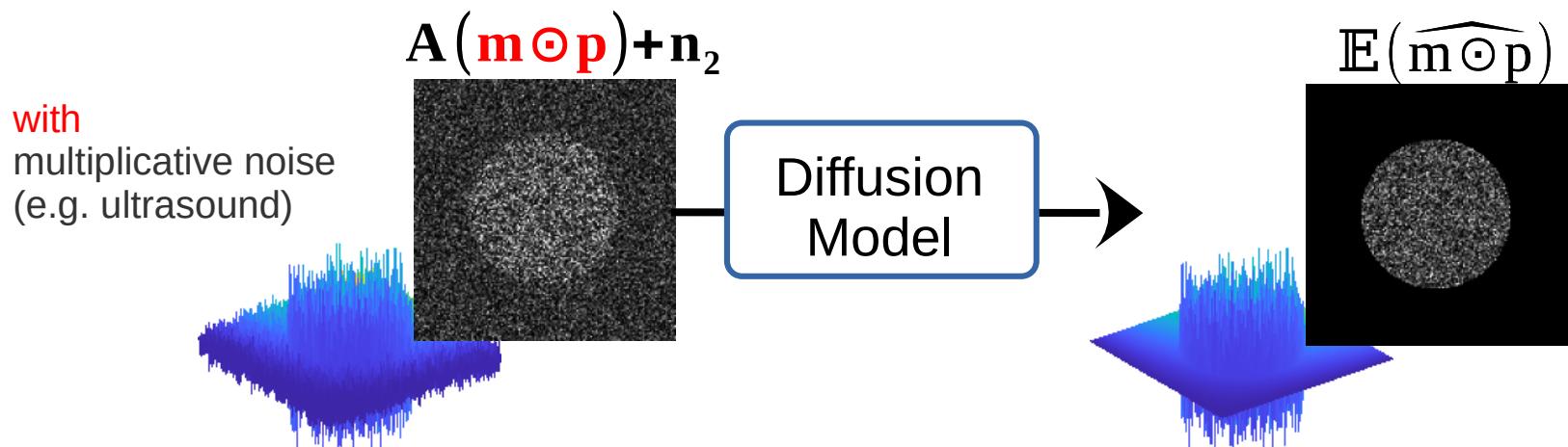
Diffusion Variance Behavior



Variance of diffusion samples inform the level of the multiplicative noise

Diffusion Variance Behavior

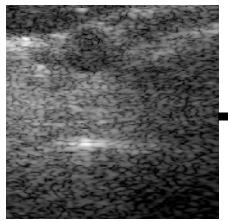
Variance of diffusion samples inform the level of the multiplicative noise



Workflow

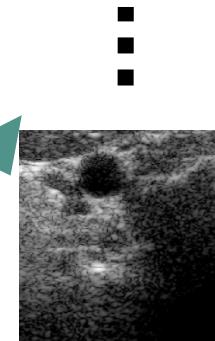
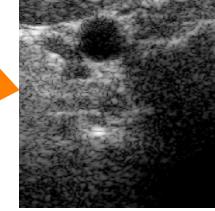
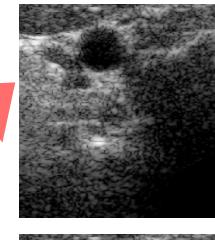
$$\mathbf{f} = \mathbf{A}(\mathbf{m} \odot \mathbf{p}) + \mathbf{n}$$

RF image \mathbf{f}



Diffusion Model

(50 iterative
steps is sufficient)



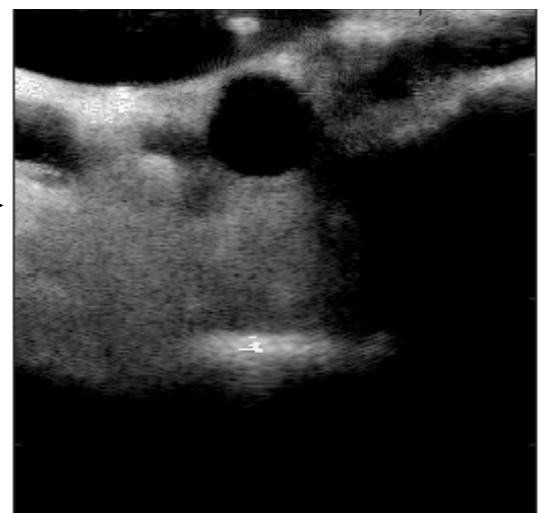
$\widehat{(\mathbf{m} \odot \mathbf{p})}$

Sample 1

Sample 2

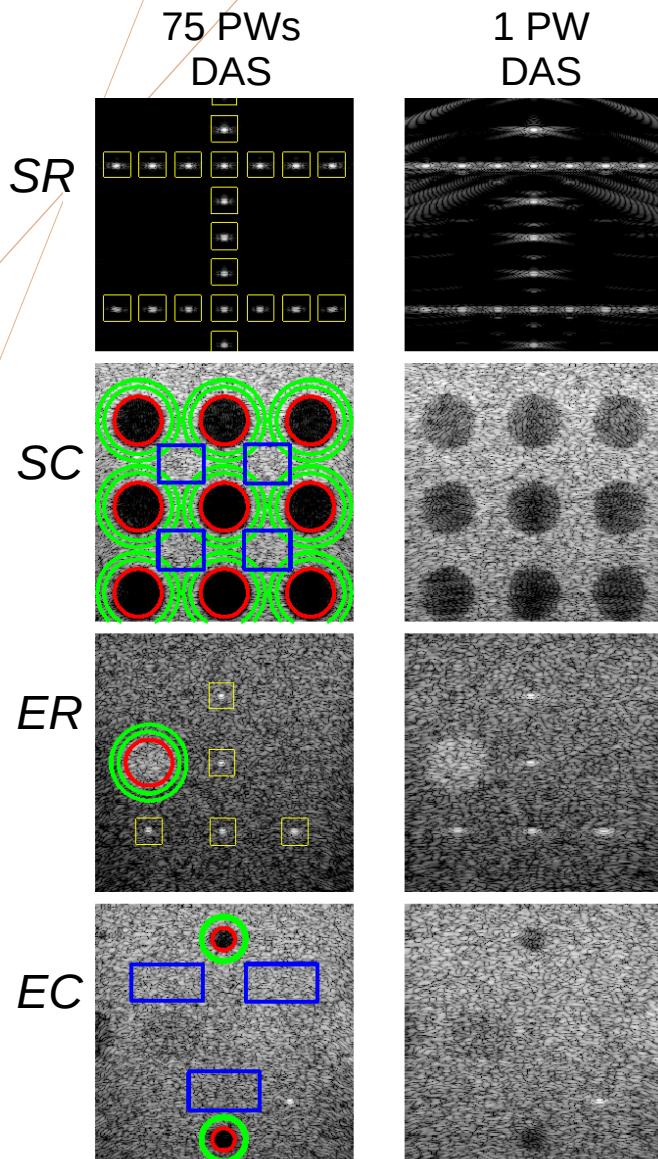
Sample 10

Variance

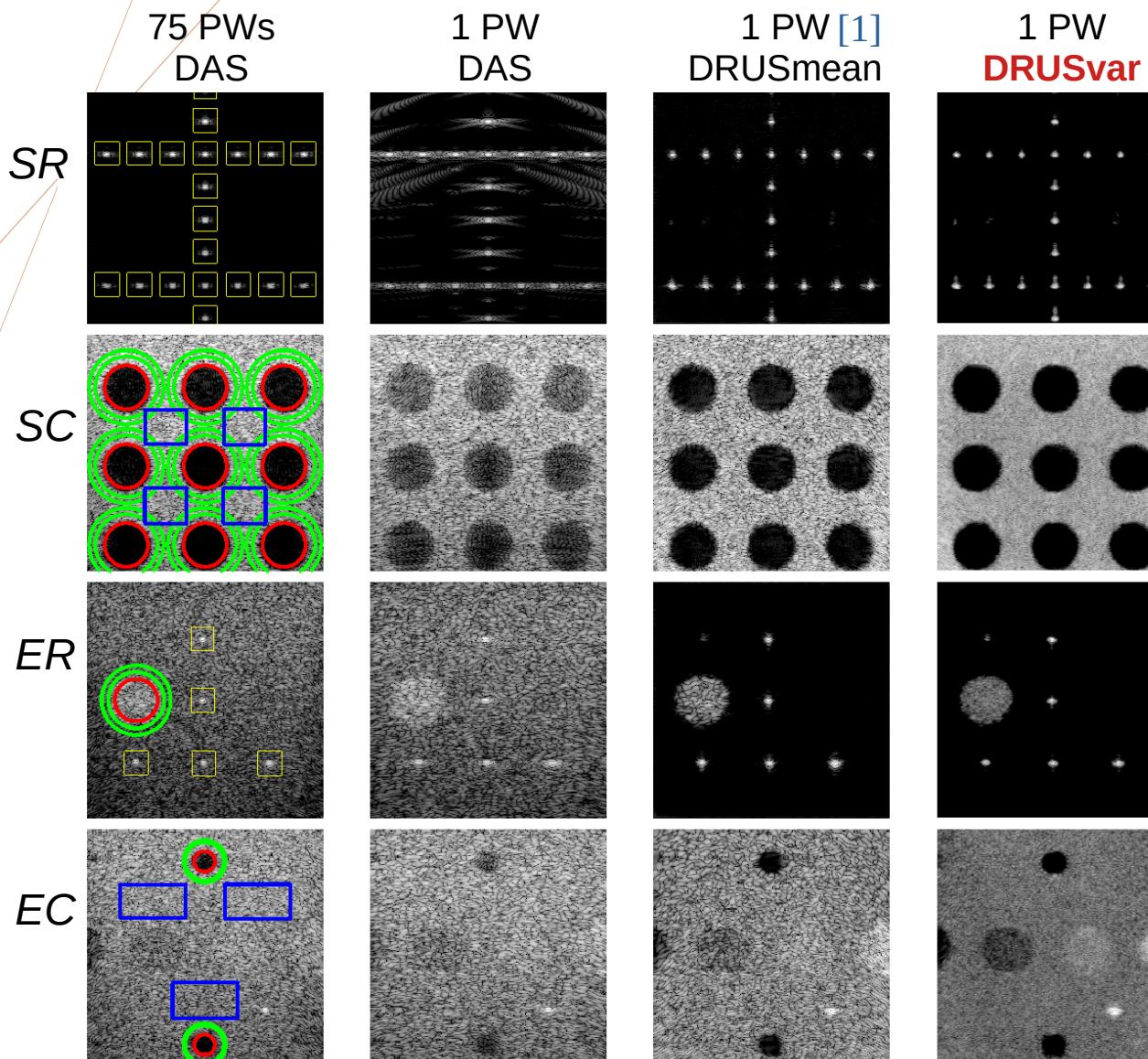


$\widehat{\mathbf{p}}$

On Simulated & Experimental Datasets

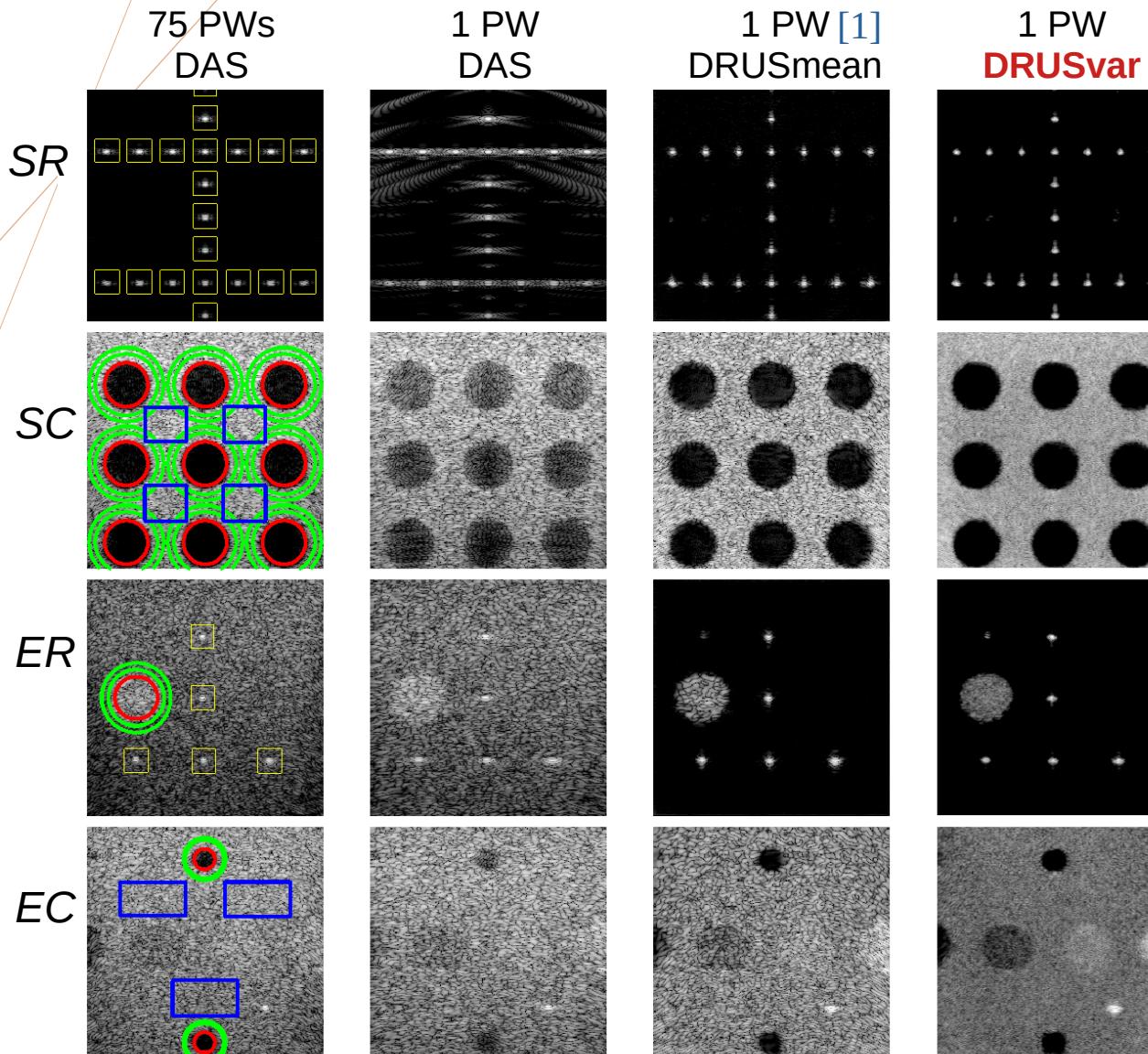


On Simulated & Experimental Datasets



[1] Y. Zhang et al., Ultrasound image reconstruction with denoising diffusion restoration models. MICCAI, 2023

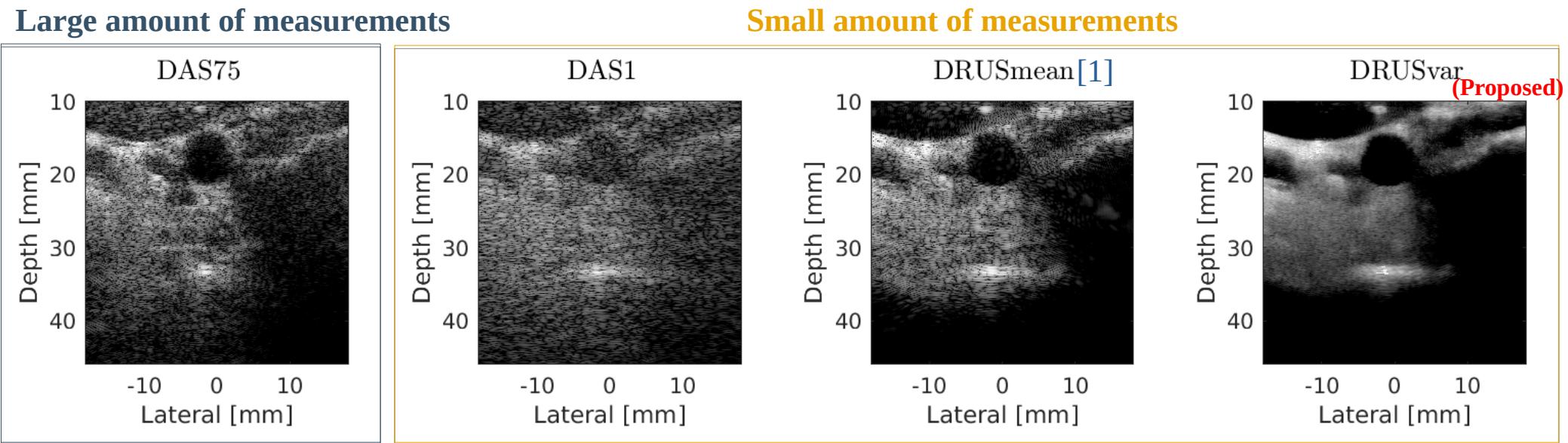
On Simulated & Experimental Datasets



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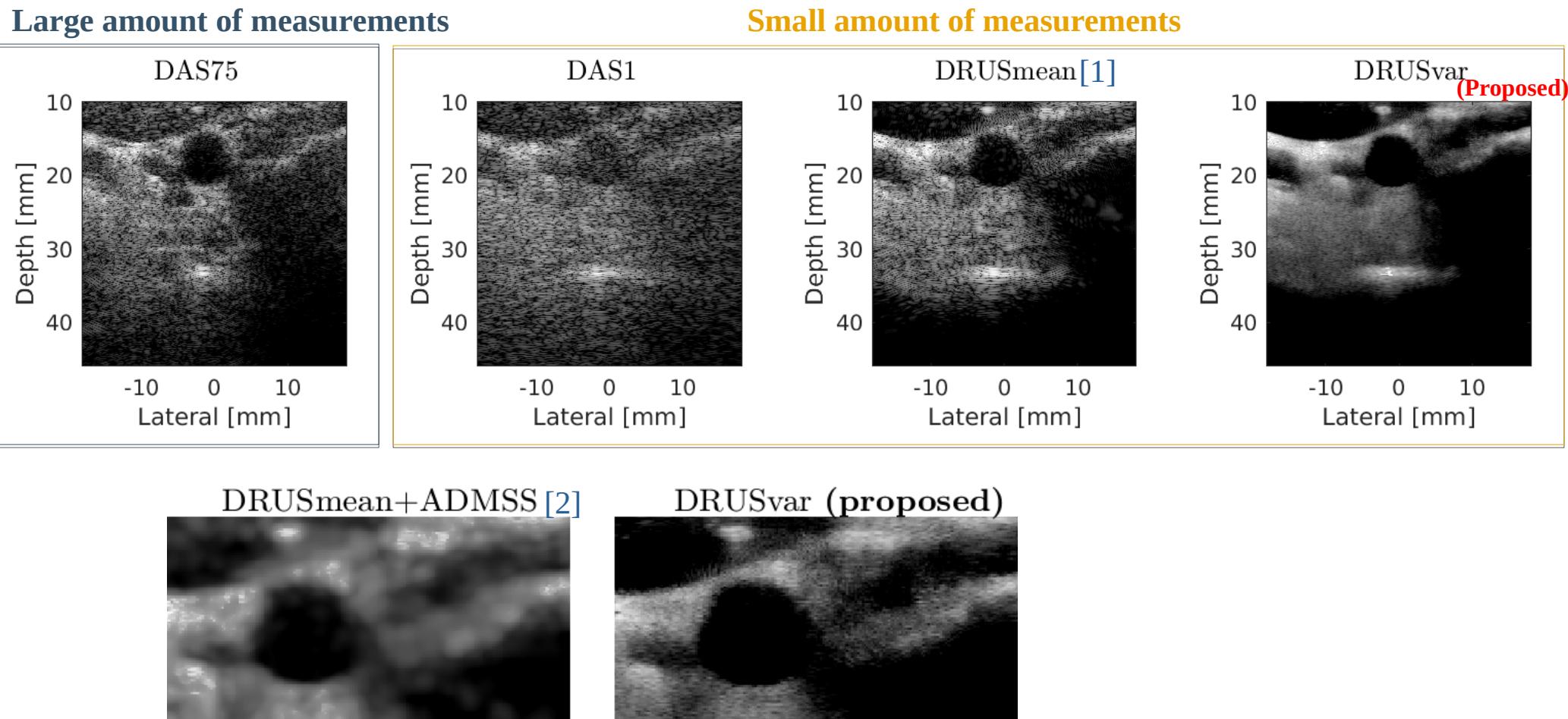
On an *In-Vivo* Dataset

*Carotid
Cross*



On an *In-Vivo* Dataset

*Carotid
Cross*



Take-Home Message

Problem: Ultrasound Despeckling

Contribution:

Adapt the most **Realistic Model**, and solve an **Inverse Problem**

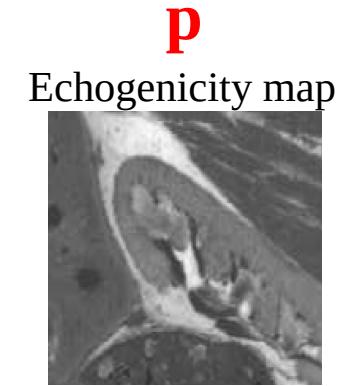
$$\mathbf{f} = \mathbf{A}(\mathbf{m} \odot \mathbf{p}) + \mathbf{n}$$

Reveal that **Variance of diffusion samples \propto level of the multiplicative noise**

$$\text{Var}(\widehat{\mathbf{m}} \odot \widehat{\mathbf{p}}) \rightarrow \hat{\mathbf{p}}$$

Current Challenges:

- The requirement of the **SVD(A)**
- **Non-real-time** reconstruction (1.25sec/iter --> 1min/sample)

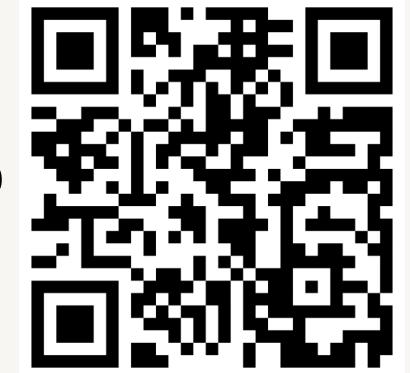




THANK YOU!

yuxin.zhang@ls2n.fr

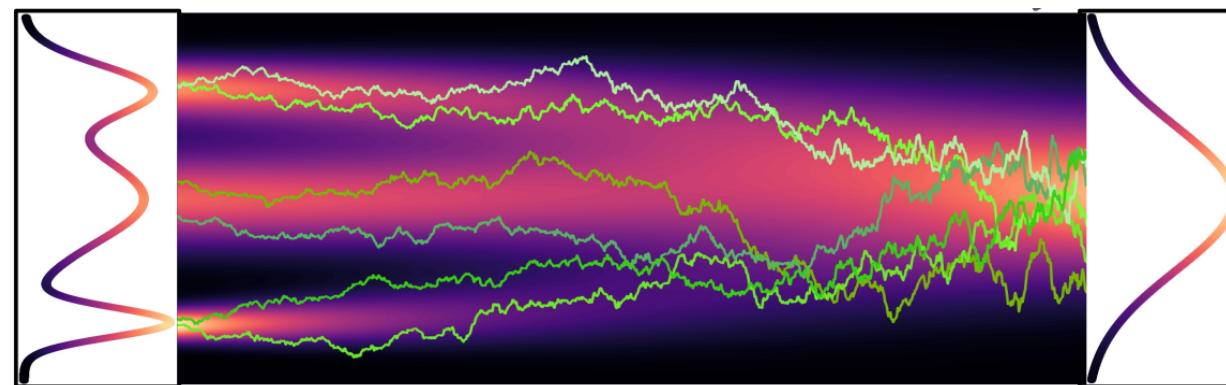
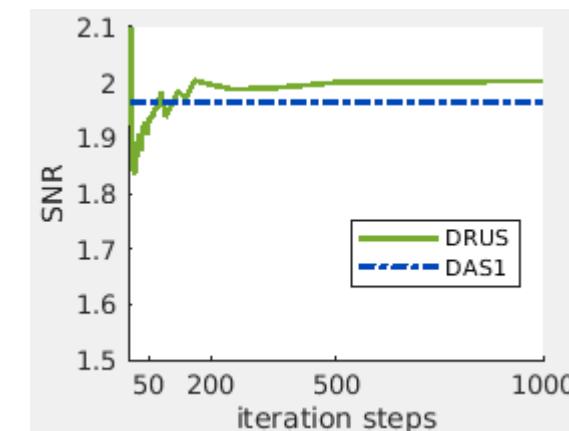
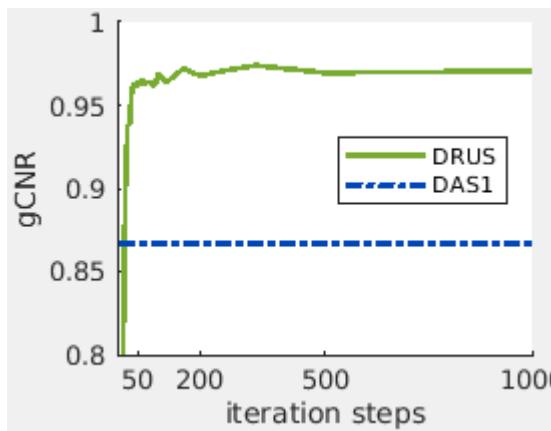
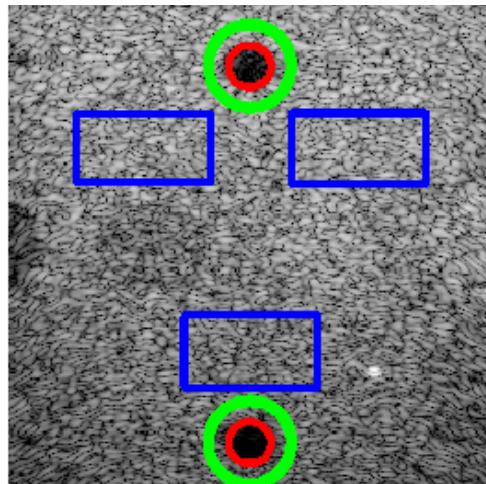
Github
Code



Paper



Sensitivity to the Number of Iterative Steps (for a single sample)



←

50 steps is good!

Sensitivity to the Number of Samples

